

$$a) v(\vec{p}, y) = f(y) p_1^{\alpha_1} p_2^{\alpha_2} p_3^{\alpha_3}.$$

Given the properties in THEOREM 1.6, we must have:

① $f(y)$ continuous in y . ✓

② Homo. of deg. 0 in $(\vec{p}, y)$ implies

$$f(ty) (tp_1)^{\alpha_1} (tp_2)^{\alpha_2} (tp_3)^{\alpha_3} = f(y) p_1^{\alpha_1} p_2^{\alpha_2} p_3^{\alpha_3}$$

$$\Rightarrow f(ty) t^{\alpha_1 + \alpha_2 + \alpha_3} = f(y)$$

$$\Rightarrow f(ty) = t^{-(\alpha_1 + \alpha_2 + \alpha_3)} f(y)$$

$\Rightarrow f(y)$ is homo. of deg. $-(\alpha_1 + \alpha_2 + \alpha_3)$. ✓

③ v strictly increasing in y implies $f'(y) > 0$. ✓

④ v decreasing in $\vec{p}$ implies:

$$\alpha_1, \alpha_2, \alpha_3 < 0. \quad \checkmark$$

⑤ Quasiconvex in $(\vec{p}, y)$ implies:

$v(\vec{p}, y)$ is quasi-convex iff $-v(\vec{p}, y)$ is quasi-concave.

A necessary condition for $-v(\vec{p}, y)$ to be quasi-concave is:

1.56) a) cont'd

1.56 (1')

$$(-1)^n D_n(\vec{p}, y) \geq 0$$

(Unfortunately, this is not given in Jekle & Reny.)

where $D_n = \begin{vmatrix} 0 & \frac{\partial \bar{v}}{\partial p_1} & \frac{\partial \bar{v}}{\partial p_2} & \frac{\partial \bar{v}}{\partial p_3} & \frac{\partial \bar{v}}{\partial y} \\ \frac{\partial \bar{v}}{\partial p_1} & \frac{\partial^2 \bar{v}}{\partial p_1^2} & \frac{\partial^2 \bar{v}}{\partial p_1 \partial p_2} & \dots & \frac{\partial^2 \bar{v}}{\partial p_1 \partial y} \\ \frac{\partial \bar{v}}{\partial p_2} & \cdot & \cdot & \cdot & \cdot \\ \frac{\partial \bar{v}}{\partial p_3} & \cdot & \cdot & \cdot & \cdot \\ \frac{\partial \bar{v}}{\partial y} & \cdot & \cdot & \cdot & \frac{\partial^2 \bar{v}}{\partial y^2} \end{vmatrix}$

$$\bar{v} = -v.$$

$$(-1)^1 D_1 = \left(\frac{\partial \bar{v}}{\partial p_1} \right)^2 = \left(\frac{\alpha_1 v(p, y)}{p_1} \right)^2 \geq 0 \quad (\text{not useful b/c always true.})$$

$$(-1)^2 D_2 = \begin{vmatrix} 0 & \bar{v}_1 & \bar{v}_2 \\ \bar{v}_1 & \bar{v}_{11} & \bar{v}_{12} \\ \bar{v}_2 & \bar{v}_{21} & \bar{v}_{22} \end{vmatrix} \geq 0$$

The above inequality must hold for $-v(\vec{p}, y)$ to be quasi-concave. It is a long procedure, but that's how I would do it...

1.56 b)

$$v(p_1, p_2, y) = u(p_1, p_2) + z(p_1, p_2)/y$$

① Continuous in $\vec{p}$ ✓② Homo. of deg. 0 in $(\vec{p}, y)$:

$$u(tp_1, tp_2) + \frac{z(tp_1, tp_2)}{ty} = u(p_1, p_2) + \frac{z(p_1, p_2)}{y}$$

 $\Rightarrow u(p_1, p_2)$ is homo. of deg. 0 in (p_1, p_2) . $z(p_1, p_2)$ is homo. of deg. 1 in (p_1, p_2) .③ v strictly increasing in y implies:

$$z(p_1, p_2) < 0.$$

④ v decreasing in $\vec{p}$ implies:

$$\frac{\partial u}{\partial p_i} < 0, i=1, 2. \text{ (Suppose } y \rightarrow \infty.)$$

$$\frac{\partial z}{\partial p_i} < 0, i=1, 2. \text{ (Suppose } y \rightarrow 0.)$$

⑤ Quasiconvex in $(\vec{p}, y)$: $-v(\vec{p}, y)$ quasi-concave?

$$-v = -u(p_1, p_2) - \frac{z(p_1, p_2)}{y}$$

A necessary condition:

$$(-1)^n D_n \geq 0$$

$$D_n = \begin{vmatrix} 0 & -(\mu_1 + \frac{z_1}{y}) & -(\mu_2 + \frac{z_2}{y}) & \frac{z}{y^2} \\ -(\mu_1 + \frac{z_1}{y}) & -(\mu_{11} + \frac{z_{11}}{y}) & -(\mu_{12} + \frac{z_{12}}{y}) & \frac{z_1}{y^2} \\ -(\mu_2 + \frac{z_2}{y}) & & & \vdots \\ \frac{z}{y^2} & & & -\frac{2z}{y^3} \end{vmatrix}$$

WOW!