

MICRO IV
MID-TERM FALL 2008
SOLUTIONS.

A.1

A.1) $e(\vec{p}, u)$ is homo. of deg. 1 in $\vec{p}$?
TRUE.

DEMO: We have $e(\vec{p}, u) = \vec{p} \alpha(\vec{p}, u)$
and $e(t\vec{p}, u) = t\vec{p} \alpha(t\vec{p}, u)$.

We must show that $e(t\vec{p}, u) = t e(\vec{p}, u)$.

Assume not. Then, by expenditure minimization, we must have

$$t\vec{p} \alpha(t\vec{p}, u) < t\vec{p} \alpha(\vec{p}, u).$$

$$\Rightarrow \vec{p} \alpha(t\vec{p}, u) < \vec{p} \alpha(\vec{p}, u).$$

This implies that $\alpha(\vec{p}, u)$ does not minimize expenditure at $\vec{p}$.

A contradiction.

$$\Rightarrow e(t\vec{p}, u) = t e(\vec{p}, u) \quad \underline{QED.}$$

$$A.2) \quad \mathcal{L}(\vec{m}, y) = A m_1^2 m_2^3 y$$

$$\begin{aligned} a) \quad \mathcal{L}_1(\vec{m}, y) &= \frac{\partial \mathcal{L}}{\partial m_1} \quad \text{by Shephard's lemma.} \\ &= \alpha A m_1^{\alpha-1} m_2^3 y \\ &= \frac{\alpha \mathcal{L}(\vec{m}, y)}{m_1} \end{aligned}$$

Similarly for $\mathcal{L}_2(\vec{m}, y)$.

$$\begin{aligned} b) \quad \mathcal{L}_1 &= m_1 \mathcal{L}_1 / \mathcal{L} \\ &= \frac{\alpha A m_1^{\alpha} m_2^3 y}{A m_1^2 m_2^3 y} = \alpha, \quad \text{QED} \end{aligned}$$

Similarly for $\mathcal{L}_2$.

$$A.3) \quad \eta_i = \frac{\frac{\partial x_i}{x_i}}{\frac{\partial y}{y}}$$

By budget balancedness, we have

$$\sum_i p_i x_i = y$$

$$\Rightarrow \frac{\partial}{\partial y} \sum_i p_i x_i = 1$$

$$\Rightarrow \sum_i \left[p_i \frac{\partial x_i}{\partial y} \right] = 1$$

$$\Rightarrow \sum_i \left[p_i \frac{\partial x_i}{\partial y} \cdot \frac{y}{x_i} \cdot \frac{x_i}{y} \right] = 1$$

$$\Rightarrow \sum_i \left[\frac{p_i x_i}{y} \frac{\frac{\partial x_i}{x_i}}{\frac{\partial y}{y}} \right] = 1$$

$$\Rightarrow \sum_i x_i \eta_i = 1. \quad \underline{QED}$$

B.1 Hom. of degree 0 implies:

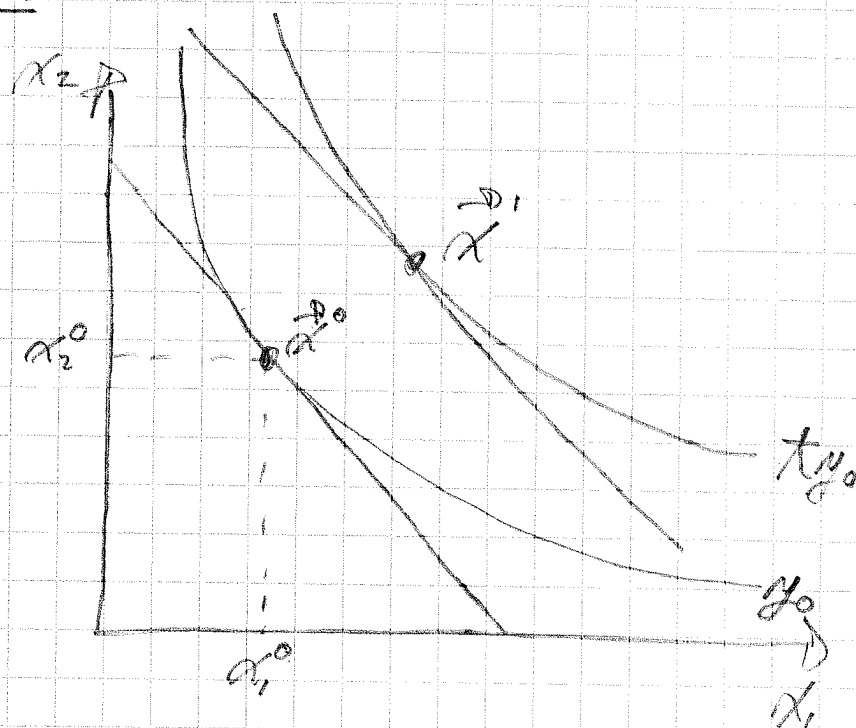
B1

$$\vec{x}(\vec{m}, y) = \vec{x}(t\vec{m}, ty) \dots$$

This is FALSE.

$$\vec{x}^0 = \vec{x}(\vec{m}, y^0)$$

$$\vec{x}^1 = \vec{x}(t\vec{m}, ty^0)$$



cf. $t > 1$, then we have $ty^0 > y^0$ while the slope of the isocost curve is unchanged. In this example, we get $\vec{x}(t\vec{m}, ty^0) \gg \vec{x}(\vec{m}, y^0)$. Hence the conditional demand is not hom. of deg. 0 in $(\vec{m}, y)$.

The bottom line is that you cannot produce more output with the same input vectors.

B.2

a) By budget balancedness, we have $p_1 x_1 + p_2 x_2 + p_3 x_3 = y$.

$$\Rightarrow x_3(\vec{p}, y) = \frac{y - p_1 x_1 - p_2 x_2}{p_3}$$

All is left to do is to substitute $x_1(\vec{p}, y)$ and $x_2(\vec{p}, y)$ to get $x_3(\vec{p}, y)$.

b) The Marshallian demands should be homogeneous of degree 0 in $(\vec{p}, y)$, i.e. $x_i(t\vec{p}, ty) = x_i(\vec{p}, y)$.

We have

$$\begin{aligned} x_1(t\vec{p}, ty) &= 100 - 5 \frac{tp_1}{tp_3} + B \frac{tp_2}{tp_3} + \frac{5ty}{tp_3} \\ &= 100 - 5 \frac{p_1}{p_3} + B \frac{p_2}{p_3} + \frac{5y}{p_3} \\ &= x_1(\vec{p}, y) \quad \underline{\text{QED}} \end{aligned}$$

And similarly for $x_2(\vec{p}, y)$.

c) By symmetry of the Slutsky matrix, we have:

$$\frac{\partial x_1}{\partial p_2} + x_2 \frac{\partial x_1}{\partial y} = \frac{\partial x_2}{\partial p_1} + x_1 \frac{\partial x_2}{\partial y}$$

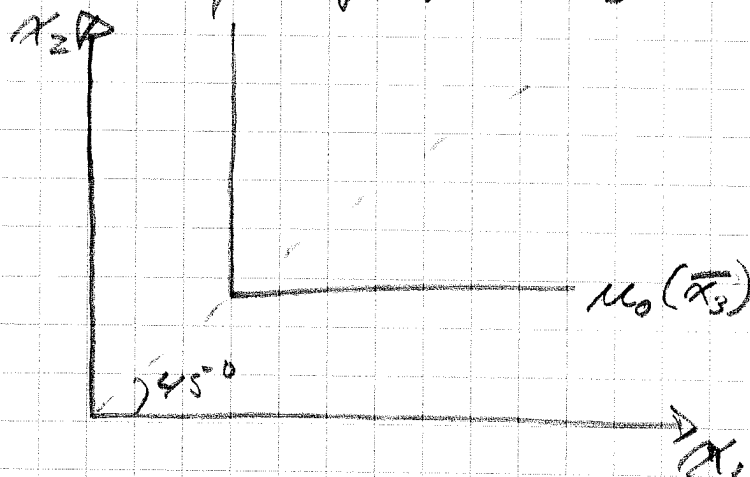
$$\Rightarrow \frac{B}{p_3} + x_2 \frac{5}{p_3} = \frac{B}{p_3} + x_1 \frac{5}{p_3} \Rightarrow x_2 = x_1$$

$$\Rightarrow 100 - 5 \frac{p_1}{p_3} + \beta \frac{p_2}{p_3} = \alpha + \beta \frac{p_1}{p_3} + \gamma \frac{p_2}{p_3}$$

$$\Rightarrow \alpha = 100, \beta = -5 = \gamma. \quad \text{QED}$$

3 d) Since $x_1 = x_2$, we have a Leontief utility function for fixed x_3 !

$$\Rightarrow u(x_1, x_2, \bar{x}_3) \\ = u(\min\{x_1, x_2\}, \bar{x}_3)$$



4 e) By negative semi-definiteness of the Slutsky matrix, we have

$$\frac{\partial x_1}{\partial p_1} + x_1 \frac{\partial x_1}{\partial y} \leq 0.$$

$$\Rightarrow -\frac{5}{p_3} + x_1 \frac{5}{p_3} \leq 0$$

$$\Rightarrow \delta x_1 \leq 5$$

$$\Rightarrow \delta(100 - 5 \frac{p_1}{p_3} - 5 \frac{p_2}{p_3} + 5 \frac{y}{p_3}) \leq 5$$

Since y is unbounded above, we can always find y large enough such that this inequality is violated when $\delta^2 > 0$.

$$\Rightarrow \delta = 0. \quad \text{QED}$$

